CY Wireless Technology Limited

Built-in Clock, Calibration Free, Single PhaseEnergy Meter IC with Integrated Oscillator

CYP1840 Datasheet

Date：2021/09/08Version：1.03

General Description

CYP1840 is a built-in clock and calibration-free energy metering IC, suitable for single-phase multifunctional electricity meter, smart socket, smart home appliances, electric bicycle charging pile and other applications with better cost performance.

CYP1840 integrates 2 high-precision sigma-delta ADC to measure current and voltage simultaneously. Reference voltage, power management and other analog circuit modules, and processing active power, current and voltage RMS electrical parameters digital signal processing circuit.

CYP1840 can measure electric parameters such as current and voltage RMS, active power, active energy, fast current RMS (for leakage detection/over-current protection), and temperature detection, waveform output and so on. CYP1840 output data through the UART/SPI interface. It is available for the smart socket, smart appliances, single-phase multi-function power meter, electric bicycle charging pile and information requirement of data acquisition in electricity applications.

CYP1840 has a patented anti-creep design, which can be combined with reasonable external hardware design to ensure that the noise energy cannot be calculated in the energy pulse when there is no load.

Features

- 2 high-precision sigma-delta ADC for current and voltage measuring
- The range of current（10mA~35A）@1mohm
- The range of Active energy（1w~7700w）@1mohm@220V
- Measure RMS Voltage and Current, fast current RMS, Active Power, Active Energy
- The gain error is less than 1%, calibration-free when peripheral components meet certain conditions.
- The current channel support electric leakage/over-current monitoring function, the threshold and response time can be configured
- Voltage zero-Crossing logic output
- Built-in waveform register for load type analysis, Waveform data can be output for load type analysis
- Built-in temperature sensor, Meet the requirements of the product itself, such as over-temperature monitoring, high current node preset temperature alarm, room temperature measurement
- SPI（≤900KHz）/UART（4800bps）
- On-chip power supply monitoring, IC reset when VDD is lower than 2.7V(typical).
- On-chip voltage reference of 1.218V
- On-chip 4MHz oscillator circuit
- Power supply 3.3V, low power consumption 10mW (typical)
- Package：TSSOP14

Order specification

Part No	Package	Manner of Packing	Devices per bag/reel
CYP1840	TSSOP14	Reel	3000PCS

Block Diagram

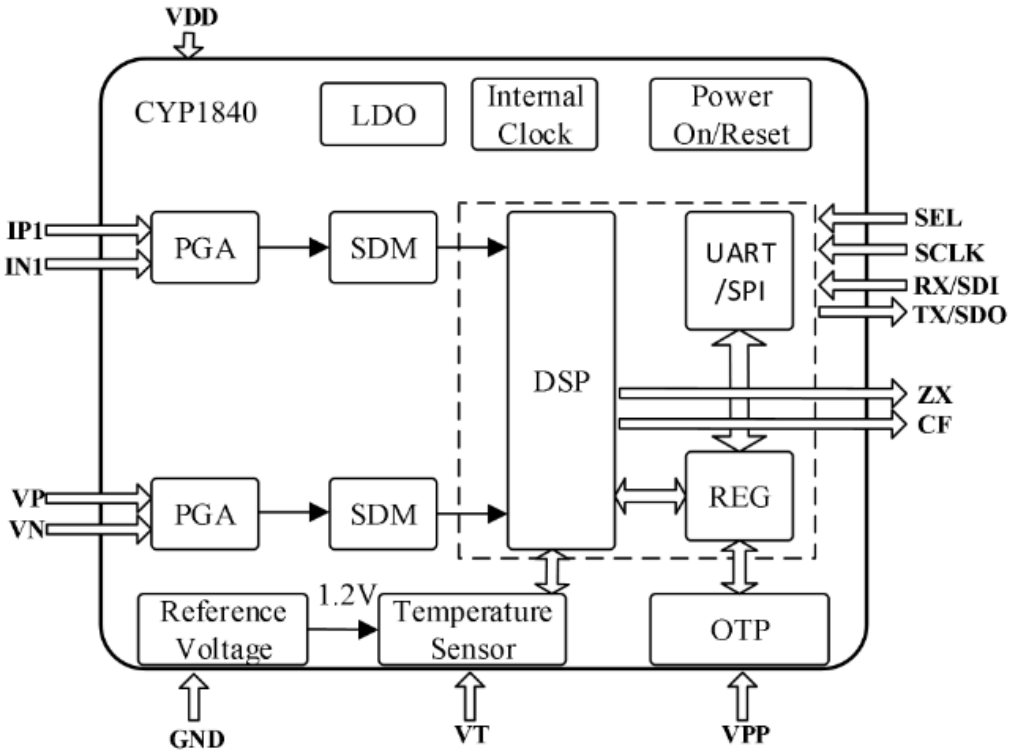


Figure 1 Internal block diagram

Pin Assignment

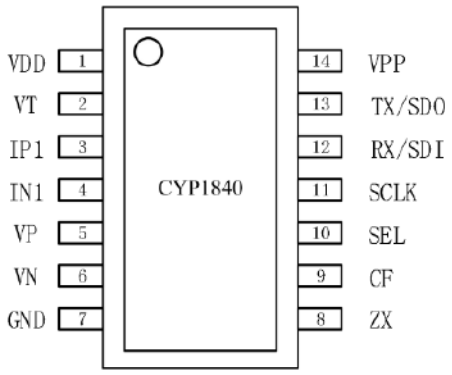


Figure 2 TSSOP14

Pin No.	Pin Name	Description
1	VDD	Power Supply (+3.3V).
2	VT	External temperature sensor(NTC) signal input.
3,4	IP1,IN1	Analog input of current channel, maximum differential voltage has a maximum input range of ±50mV(35mV RMS).
5,6	VP,VN	Analog input for voltage channel, this differential input has a maximum input range of ±100mV(70mV RMS).
7	GND	GND
8	ZX	Voltage channel zero-crossing output pin
9	CF	Energy pulse output, multiplex function refer to MODE register description
10	SEL	Interface select pin (0: UART 1: SPI), pull-down resistance inside, disconnect is low-level (UART), connected to VDD is high-level (SPI)
11	SCLK	SPI clock input. If using UART interface, this pin doesn't need be connected.
12	RX/SDI	Data input for SPI interface/Receive line for UART interface
13	TX/SDO	Data output for SPI interface/Transmit line for UART interface, this pin require external pull-up resistor.
14	VPP	Reserved, not connected.

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Power Voltage VDD	VDD	-0.3～+4	V
Analog Input Voltage to GND	IP1,VP	-4～+4	V
Digital Input Voltage to GND	UART_SEL,RX/SDI	-0.3～VDD+0.3	V
Digital Output Voltage to GND	CF,TX/SDO	-0.3～VDD+0.3	V
Operating Temperature Range	T	-40～+85	℃
Storage Temperature Range	Tstg	-40～+85	℃

Note: Unless specified otherwise, Tamb= 25℃

Electrical Characteristics

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Power Supply	VDD		3.0		3.6	V
Power Dissipation	Iop	VDD=3.3V		3		mA
Measuring range		4000:1 Input dynamic range				
Active energy measurement accuracy (large signal)		35A~100mA Input@ 1mohm sampling resistor		0.2		%
Active energy measurement accuracy (small signal)		100mA~50mA Input@ 1mohm sampling resistor		0.4		%
Active energy measurement accuracy (tiny signal)		50mA~10mA Input@ 1mohm sampling resistor		0.6		%
RMS measurement accuracy(large signal)		35A~100mA Input@ 1mohm sampling resistor		0.2		%

RMS measurement accuracy(small signal)		100mA~50mA Input@ 1mohm sampling resistor		2		%
RMS measurement accuracy(tiny signal)		50mA~10mA Input@ 1mohm sampling resistor		6		%
Fast RMS response time	50Hz	Can be set to cycle/half cycle	10		40	mS
	60Hz		8.3		33	mS
Zero-crossing signal output delay				571		uS
Measurement error caused by phase angle between channels (capacitance)	PF08err	Phase advance 37 °（PF=0.8）			0.5	%
Measurement error caused by phase angle between channels (sensibility)	PF05err	Phase delay 60 °（PF=0.5）			0.5	%
AC power suppression (output frequency amplitude variation)	ACPSRR	IP/N=100mV			0.1	%
DC power suppression (output frequency amplitude variation)	DCPSRR	VP/N=100mV			0.1	%
Analog input level (current)		Differential current input (peak)			50	mV
Analog input level (voltage)		Differential voltage input (peak)			200	mV
Analog input impedance				370		kΩ
SEL pull-down resistor		SEL（pull-down）		56.9		kΩ
Analog input bandwidth		（-3dB）		3.5		kHz
Internal voltage reference	Vref			1.218		V
Logic input high-level		VDD=3.3V±5%	2.6			V
Logic input low-level		VDD=3.3V±5%			0.8	V
Logic output high-level		VDD=3.3V±5% IOH=5mA	VDD -0.5			V
Logic output low-level		VDD=3.3V±5% IOL=5mA			0.5	V

Note: Unless specified otherwise, Tamb = 25℃

All voltage values take GND terminal potential as reference point.

Test conditions VDD=3.3V, Built-in crystal oscillator, electric energy is measured by CF output.

Internal Register Description

Register list

Address	Symbol	External R/W	Internal R/W	Bits	Default	Description
Electrical parameter register (read only)						
0x00	IA_FAST_RMS	R	W	24	0x000000	Fast current RMS, unsigned
0x01	IA_WAVE	R	W	20	0x00000	Current waveform register, signed
0x03	V_WAVE	R	W	20	0x00000	Voltage waveform register, signed
0x04	IA_RMS	R	W	24	0x000000	Current RMS register, unsigned
0x06	V_RMS	R	W	24	0x000000	Voltage RMS register, unsigned
0x08	A_WATT	R	W	24	0x000000	Active power register, signed
0x0A	CFA_CNT	R	W	24	0x000000	Active energy pulse count, unsigned
0x0C	A_CORNER	R	W	16	0x0000	Current voltage waveform phase angle register
0x0E	TPS1	R	W	10	0x000	Internal temperature register, unsigned
0x0F	TPS2	R	W	10	0x000	External temperature register, unsigned
User operated register (read and write)						
0x10	IA_FAST_RMS_CTRL	R/W	R	16	0xFFFF	Fast current RMS control register
0x11	IA_CHOS	R/W	R	8	0x00	Current DC offset correction
0x13	IA_RMSOS	R/W	R	8	0x00	Current RMS offset adjust register
0x15	A_WATTOS	R/W	R	8	0x00	Active power offset adjust register
0x17	WA_CREEP	R/W	R	8	0x0B	Active power no-load threshold register
0x18	MODE	R/W	R	16	0x0000	User mode selection register
0x19	SOFT_RESET	R/W	R	24	0x000000	When 0x5A5A5A is written, the user area register is reset to default
0x1A	SR_WRPR OT	R/W	R	8	0x00	Write protection register. After writing 0x55, the user operation register can be written. Write other values, user operated register area is not writable
0x1B	TPS_CTRL	R/W	R	16	0x07FF	Temperature mode control register
0x1C	TPS2_A	R/W	R	8	0x0000	External temperature sensor gain coefficient adjust register
0x1D	TPS2_B	R/W	R	8	0x0000	External temperature sensor offset coefficient adjust register

Special Register Description

User mode selection register（Note: X indicates either 0 or 1）

0x18	MODE	User mode selection register		
No.	name	default value	description	
[1:0]	IA_F_SEL	0b00	Current waveform selection through filter	0X：High pass, AC measurement
				10：Low pass, DC measurement
				11：Full wave, AC/DC measurement
2~3	reserved	0b00	reserved	
[5:4]	V_F_SEL	0b00	Voltage waveform selection through filter	0X：High pass, AC measurement
				10：Low pass, DC measurement
				11：Full wave, AC/DC measurement
6	L_F_SEL	0b0	Fast effective value selection through filter	0：High pass filter front output
				1：High pass filter behind output
7	reserved	0b00	reserved	
8	RMS_UPDATE _SEL	0b0	RMS register update rate	0：400ms
				1：800ms
9	AC_FREQ_SEL	0b0	AC frequency select	0：50Hz
				1：60Hz
10	Reserved	0b0	reserved	
11	Reserved	0b0	reserved	
12	CF_UNABLE	0b0	CF output function selection	0：reserved
				1：Over-current alarm function enable by TPS_CTRL[14] configured
13~15	Reserved	3b000	reserved	

Temperature mode control register

0x1B	TPS_CTRL	Temperature mode control register		
No.	name	default value	description	
			[15] Temperature switch, default 0b0,Open the temperature measurement	0：on
				1：off
			[14] Alarm switch, default 0b0,	0：Temperature alarm on
				1：Over-current and leakage alarm on

0x1B	TPS_CTRL	0x07FF	[13:12]] Temperature measurement selection, default0b00 Automatic temperature measurement	00：Automatic temperature measurement
				01：the same as 00
				10：Internal temperature measurement
				11：External temperature measurement
			[11:10]Temperature measurement interval default0b01 100ms	00：50ms
				01：100ms
				10：200ms
				11：400ms
			[9:0] External temperature measurement alarm thresholdsetting, default 0x3FF,not alarm	Alarm when TPS2 register value isgreater than or equal to it.

Theory of Operation

CYP1840 is composed of analog signal processing module and digital signal processing module. The analog module includes two-channel PGA, two-channel sigma-delta ADC, internal clock, power on/reset monitor, temperature sensor and other related analog modules. The digital module is digital signal processing module (DSP).

Current and voltage transient waveform measurement

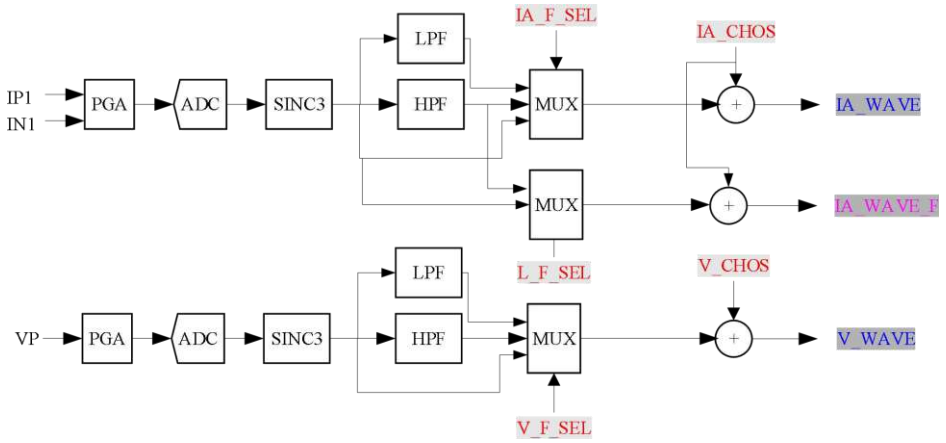


Figure 4

As shown in the figure above, the current and voltage pass through the analog module amplifier (PGA) and the high-precision analog-to-digital conversion (ADC) respectively to get two channels of 1bit PDM to the digital module. The digital module passes through the SINC3 filter (SINC3), optional high-pass filter (HPF) or low-pass filter (LPF) and channel offset correction modules. Obtain the required current waveform data and voltage waveform data (IA_WAVE, V_WAVE).

HPF and LPF are optional for the two channels. HPF is an AC measurement mode, LPF is a DC measurement mode, and full-wave measurement mode is a full-wave measurement mode if neither of them is passed. Set

through user MODE register MODE [5:0].

The current and voltage waveform data are updated at a rate of 7.8k. Each sampled data is 20bit signed value, which are saved in waveform registers (I_WAVE, V_WAVE). The waveform value can be read continuously when the SPI rate is greater than 375Kbps.

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x01	IA_WAVE	R	W	20	0x00000	Current waveform register
0x03	V_WAVE	R	W	20	0x00000	Voltage waveform register

Channel offset correction

The CYP1840 contains an 8-bit calibration register (IA_CHOS) with a default value of 00H. They eliminate the deviation caused by the analog-to-digital conversion of the current channel and the voltage channel respectively by the data in the form of the complement of 2. The deviation here may be due to the offset generated by the input and the ANALOG-to-digital conversion circuit itself. The offset correction allows the waveform offset to be 0 without load.

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x11	IA_CHOS	R/W	R	8	0x00	Current channel DC offset correction

These registers are used for DC measurement mode, IA/V_LPF_SEL=1。

Correction formula: $CHOS = \frac{WAVE - WAVE0}{4_2}$

WAVE is the corrected waveform value, WAVE0 is the uncorrected waveform value;

Corresponding RMS value: $RMS = RMS0 + \frac{3125 * CHOS}{4}$

RMS is the corrected valid value, RMS0 is the uncorrected valid value.

Active Power

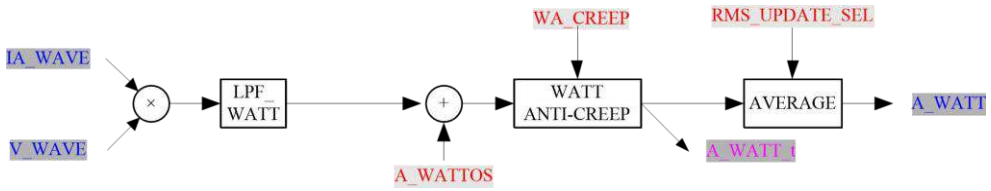


Figure 5

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x08	A_WATT	R	W	24	0x000000	Active power register

Formula for calculating active power: $A\_WATT = \frac{4046 * I\_A * V(V) * \cos(\varphi)}{Vref^2}$

I(A) and V(V) are the voltage RMS of analog input PIN(IP&IN, VP&GND), φ is the phase angle

between I(A) and V(V) (AC signal), Vref is the on-chip reference voltage, the typical value is 1.218V.

This register indicates whether the active power is positive or negative. Bit[23] is the symbol Bit. Bit [23]=0 means the current power is positive and Bit[23]=1 means the current power is negative, in complement form.

Active power offset correction

CYP1840 has one 8-bit active power offset adjust register (A_WATTOS), default value is 00H. It eliminate the offset of active power in the measurement of electric energy with the data in the form of complement of 2. Bit[7] is the symbol Bit. The offset may come from board level noise or crosstalk. Offset adjustment can make the values in the active power register close to 0 with no load.

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x15	A_WATTOS	R/W	R	8	0x00	Active power offset adjust register

$$WATTOS = \frac{WATT - WATT0}{8 \times 3.05172}$$

WATT is the active power after adjustment, and WATT0 is the active power before adjustment.

Active power anti-creep

CYP1840 has the patented power anti-creep function, which ensures that the power of board level noise will not accumulate when there is no load.

This active power no-load threshold register(WA_CREEP) is 8bit unsigned data, default value is 0BH. The corresponding relationship between this value and the active power register value is shown in the following formula. When the absolute value of the input active power signal is less than this value, the output active power is set to 0. This can make the value of the active power register is 0 and the energy does not accumulate in the case of no load, even if there is a tiny noise signal.

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x17	WA_CREEP	R/W	R	8	0x0B	Active power no-load threshold register

Set WA_CREEP based on the value of the power register A_WATT, their corresponding relationship as below:

$$WA\_CREEP = \frac{WATT}{3.0517578125 * 8}$$

When the channel is in the anti-creep state, the RMS current register of this channel is also set to 0.

Energy Measurement

CYP1840 provides energy pulse measurement. The active instantaneous power is integrated by time to get active energy and output calibration pulse CF in proportion. CFA_CNT register saves the count of output energy pulse.

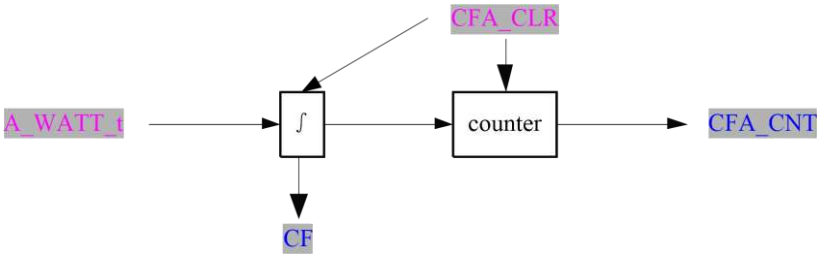


Figure 6

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x0A	CFA_CNT	R	W	24	0x000000	Active energy pulse count，unsigned

The count of active energy pulses corresponds to the consumption of electricity. The count of pulses can be counted directly from the CF pin through I/O interruption. When the period of CF is less than 180ms, the pulse is 50% duty cycle. When it is greater than or equal to 180ms, the fixed pulse width of high-level is 90ms.

Note: CFA_CNT is pulse algebraic sum accumulation. It means that pulse plus at positive energy and minus at negative energy.

The cumulative time of each CF pulse: $t_{CF}=\frac{1638.4*256}{WATT}$

WATT is the corresponding active power register value (A_WATT)

Current and Voltage RMS

The RMS of these channels is shown in the figure below. After the square circuit (X^2), the low-pass filter (LPF_RMS) and the ROOT circuit (ROOT), the instantaneous value RMS_t of RMS is calculated, and then the average value of the two channels (A_RMS, V_RMS) is calculated.

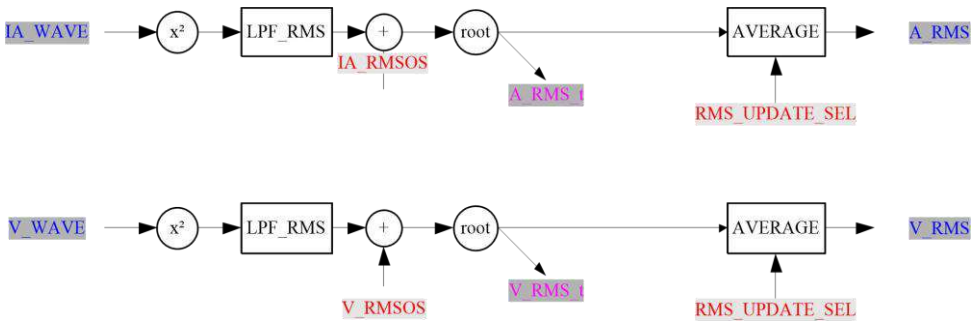


Figure 7

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x04	IA_RMS	R	W	24	0x000000	Current RMS register, unsigned
0x06	V_RMS	R	W	24	0x000000	Voltage RMS register, unsigned

0x18	MODE	User mode selection register		
No.	name	default value	description	
8	RMS_UPDATE_SEL	0b0	RMS register update rate	0：400ms
				1：800ms

Set MODE[8].RMS_UPDAT_SEL, the average refresh time of RMS can be selected as 400ms or 800ms, and the default value is 400ms. When a current channel is in anti-creep state, the RMS of the current channel is 0.

The current RMS conversion formula: $IA\_RMS = \frac{324004 * I(A)}{Vref}$

The voltage RMS conversion formula: $V\_RMS = \frac{79931 * V(V)}{Vref}$

Vref is the reference voltage, the typical value is 1.218V.

I(A) is the input signal between IP1 and IN1 pins (mV), and V(V) is the input signal of VP pins (mV).

RMS offset calibration of current and voltage

CYP1840 has one 8-bit RMS offset register (IA_RMSOS), whose default value is 00H. It is used to calibrate the deviation in RMS with the complement form of 2. Bit[7] is the sign Bit, This deviation may come from the input noise. Because there is a square operation in calculating the RMS, this may introduce DC offset caused by noise. The deviation calibration can make the value in the RMS register close to 0 without load.

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x13	IA_RMSOS	R/W	R	8	0x00	Current RMS offset adjust register

Calibration formula: $RMSOS = \frac{RMS^2 - RMS0^2}{9.3132 \times 2^{15}}$

RMS0 is the RMS current value before correcting and RMS is the RMS current value after correcting。

Leakage/Over-current Detection

CYP1840 has a fast RMS register, which can detect half cycle or cycle RMS. This function can be usedfor leakage or over-current detection. The source of waveform L_WAVE is shown below.

HPF can be passed or not passed， HPF is not passed by default， can get the absolute value of IA_WAVE_F accumulate by half-cycle or one cycle time, which is selected by FAST_RMS_CTRL[15]. Cycle accumulation is selected by default, The maximum response time is 40ms (50Hz) or 33mS (60Hz), Note that the runout of IA_FAST_RMS register is relatively large when half cycle wave accumulation ccurs. Distinguish between 50Hz and 60Hz half-cycle time (AC_FREQ_SEL).

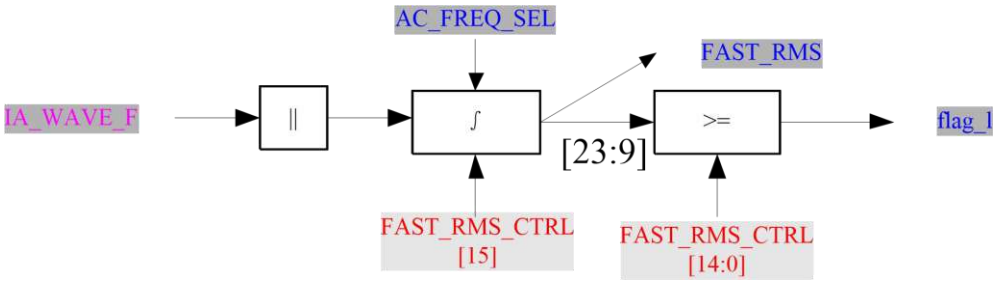


Figure 8

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x10	IA_FAST_RMS_CTRL	R/W	R	16	0xFFFF	Fast current RMS control register

Set the refresh time to half-cycle or cycle by IA_FAST_RMS_CTRL, and set the fast RMS threshold (Leakage or over-current threshold).

0x10	MODE	Fast RMS register		
No.	name	default value	description	
0x10	FAST_RMS_CTRL	0xFFFF	[15]Fast RMS refresh time	0：half-cycle
				1：cycle
			[14:0]Fast RMS threshold	

Set AC frequency by MODE[9].

0x18	MODE	User mode selection register		
No.	name	default value	description	
9	AC_FREQ_SEL	0b0	AC frequency selection	0：50Hz
				1：60Hz

Refresh the 24-bit unsigned RMS register according to one cycle or half cycle, Bit[23:9] of the FAST_RMS register compare with the leakage/over-current threshold FAST_RMS_CTRL [14:0], if the value is greater than or equal to the set threshold, then leakage/over-current alarm output pin will be highlevel.

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x00	IA_FAST_RMS	R	W	24	0x000000	Fast current RMS，unsigned

Leakage/over-current alarm output indicator pin is CF, set MODE[12]=1 and TPS_CTRL[14]=1 before use it.

0x18	MODE	User mode selection register		
No.	name	default value	description	
12	CF_UNABLE	0b0	CF output function selection	0：energy pulse, enable by MODE[11] configured

				1：Temperature measurement/Leakage alarm, enable by TPS[14] configured

0x1B	TPS_CTRL	Temperature mode control register		
No.	**name**	**default value**	**description**	
14	ALERT_CTRL	0b0	Alarm selection	0：Temperature alarm on
				1：Leakage/over-current alarm on

Since the fast effective values are updated by cycle or half-cycle, the interrupt response time is up to 2 cycles or 2 half-cycles.

Phase Angle Calculation

CYP1840 has phase angle measurement function. The reactive quadrant can be indicated by the angle of current and voltage respectively by calculating the positive zero-crossing time difference between current and voltage. It is updated to the register CORNER_A when the current is positive zero crossing.The register is a 16-bit unsigned number.

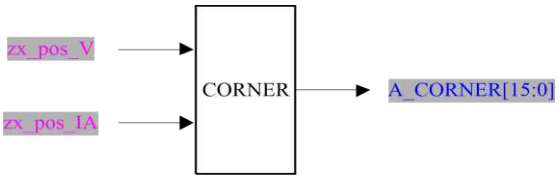


Figure 9

Address	Symbol	External	Internal	Bits	Default	Description
		R/W	R/W			
0x0C	A_CORNER	R	W	16	0x0000	Current voltage waveform phase angle register

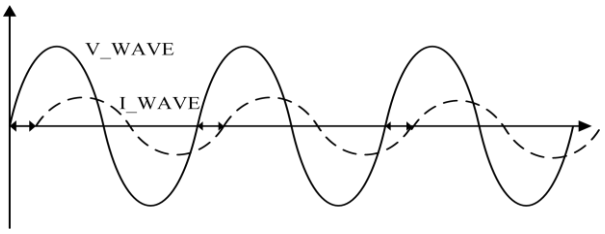


Figure 10

Phase Angle conversion formula: $2*pi*A\_CORNER*\frac{f_c}{f_0}$ The unit is radian

Among them, f_c is the frequency of the AC signal source, the default value is 50Hz. f_0 is the sampling frequency; the typical value is 1MHz.

Zero Crossing Detection

CYP1840 has the voltage zero-crossing detection function, and the zero-crossing signal is directly output by pin ZX. When ZX=0, it indicates the positive half cycle of the waveform, and when ZX=1, it indicates the negative half cycle of the waveform. The delay between the zero-crossing signal and the actual input signal is about 570us.

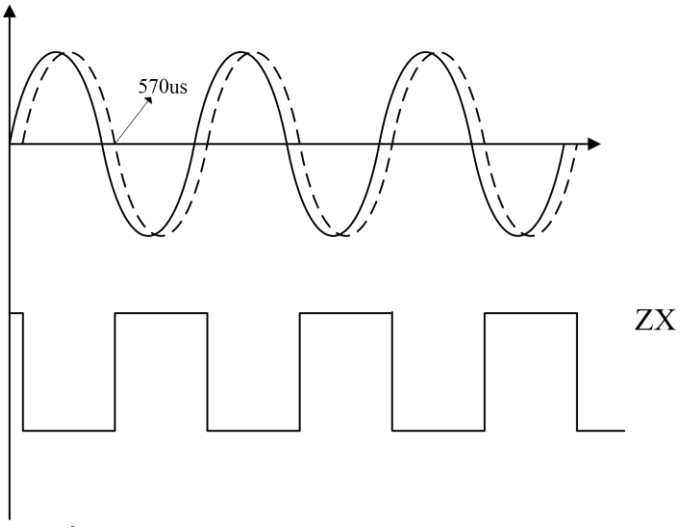


Figure 11

Temperature Measurement

CYP1840 supports internal temperature measurement and external temperature measurement.

External temperature measurement, optional output alarm indicator, Turn on the alarm function, CF pin selection output alarm signal, the CF pin will output high-level if the TPS2 is greater than or equal to the alarm threshold, Temperature indicator alarm. When the temperature value is lower than the alarm value or the alarm function is turned off, Exit alarm indicator.

0x1B	**TPS_CTRL**	**Temperature mode control register**		
No.	**name**	**default value**	**description**	
0x1B	TPS_CTRL	0x07FF	[15] Temperature measurement switch, default 0b0,Open the temperature measurement	0：on
				1：off
			[14] Alarm selection， default0b0,	0：Temperature alarm on
				1：Leakage/over-current alarm on
			[13:12]Temperature measurement selection, default 0b00 Automatic temperature measurement	00：Automatic temperature measurement
				01：the same as 00
				10：internal temperature measurement
				11：external temperature measurement
			[11:10]Temperature measurement	00：50ms

			interval selection， default 0b01 100ms	01：100ms
				10：200ms
				11：400ms
			[9:0]External temperature alarm Threshold, default 0x3FF	

First set MODE[12]=1, and then set TPS_CTRL[14]=0, then CF pin is turned on to output external temperature alarm indicator.

0x18	**MODE**	**User mode selection register**		
No.	**name**	**default value**	**description**	
12	CF_UNABLE	0b0	CF output functionselection	0：energy pulse, enable by MODE[11] configured
				1：Temperature measurement alarm, enable by TPS[14] configured

The external and internal temperature values are saved in the TPS2 and TPS1 registers respectively.

Address	**Symbol**	**External**	**Internal**	**Bits**	**Default**	**Description**
		R/W	**R/W**			
0x0E	TPS1	R	W	10	0x0000	Internal temperature register, unsigned
0x0F	TPS2	R	W	10	0x0000	External temperature register, unsigned

Internal temperature measurement formula: Tx=(170/448)(TB/2-32)-45TB

is the value in TPS1

The external temperature is measured by SAR ADC. The maximum input signal of the VT pin is0.55*VDD（V），The TPS2 register value is the corresponding AD sampling value, full scale is 1024.

Address	**Symbol**	**External**	**Internal**	**Bits**	**Default**	**Description**
		R/W	**R/W**			
0x1C	TPS2_A	R/W	R	8	0x00	External temperature sensor gain coefficient correction A register
0x1D	TPS2_B	R/W	R	8	0x00	External temperature sensor offset coefficient correction B register

Communication Interface

Register data are sent as 3 bytes (24bit). The data is fixed 3 bytes, if valid data bytes are less than 3 bytes,invalid bits are filled with 0.

SPI

- Select by pin UART_SELL, multiplex with UART
- Slave mode
- Half-duplex communication, the communication rate can be configured, the maximumcommunication rate is 900khz
- 8-bit data transmission, MSB first, LSB last
- Clock polarity / phase (CPOL = 0, CPHA = 1)

Operation Mode

The master device works in Mode1：CPOL=0，CPHA=1，In idle state, SCLK is at low-level. Data is transmitted on the first edge, which is the transition from low level to high level of SCLK, so data is received on the falling edge and data is sent on the rising edge.

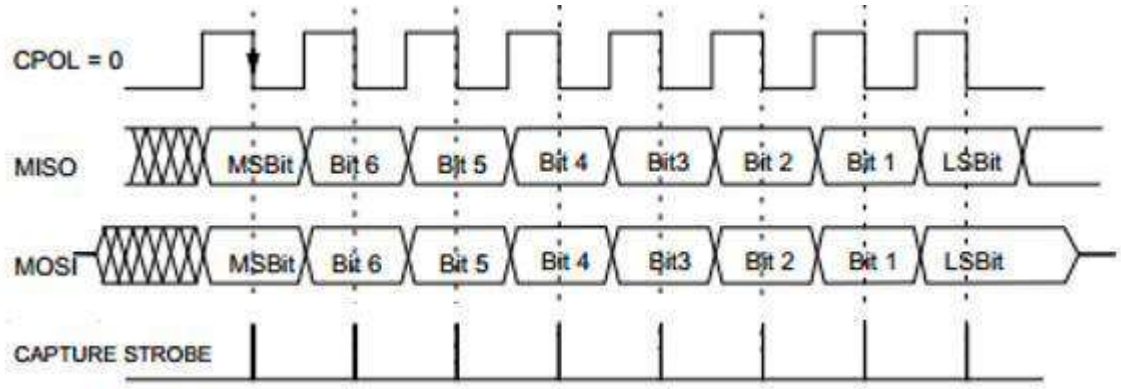


Figure 12

Frame Structure

In SPI communication mode, MCU send 8-bit identification byte (0x58) or (0xA8). (0x58) is the read operation identification byte and (0xA8) is the write operation identification byte. Then send the address byte of the register will be accessed (refer to CYP1840 register list). The below figure shows the data transfer sequence for read and write operations respectively. After one frame of data is transmitted, CYP1840 re-enters the communication mode. The number of SCLK pulses required for each reading and writing operation is 48 bits.

There are two types of frame structures, which are explained as follows: 1）

Write operation frame

Write operation frame	0xA8	ADDR[7:0]	DATA_H[7:0]	DATA_M[7:0]	DATA_L[7:0]	CHECKSUM[7:0]

The checksum byte is（（0xA8 + ADDR + DATA_H + DATA_M+ DATA_L）& 0xFF）and then bitwise inverted.

2）Read operation frame

MCU send read command frame	0x58	ADDR[7:0]

return data frame	DATA_H[7:0]	DATA_M[7:0]	DATA_L[7:0]	CHECKSUM[7:0]

The checksum byte is（（0x58 + ADDR + DATA_H + DATA_M+ DATA_L）& 0xFF）and then bitwise inverted.

Write Operation Timing

The serial write timing is performed as follows. The frame identification byte {0xA8} indicates that the data communication operation is data writing. The MCU need make the data ready before the lower edge of SCLK, and shift the data at the lower edge of this clock. All remaining bits of the data are also shifted left on the lower edge of this SCLK (Figure 13）。

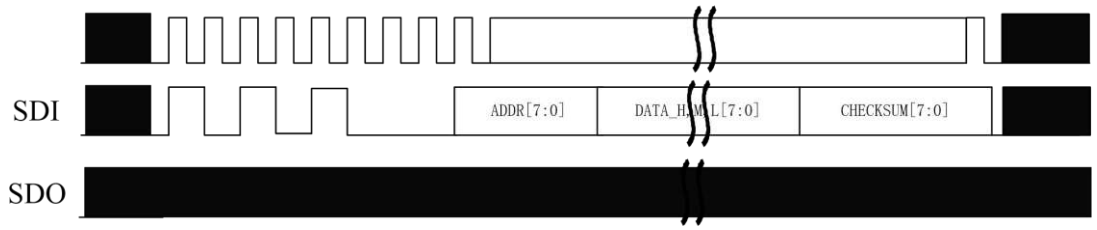


Figure 13

Read Operation Timing

During the data read operation, CYP1840 shifts the corresponding data to the DOUT pin on the rising edge of SCLK. DOUT keeps unchanged during SCLK =1.MCU can sample DOUT value before the next falling edge. MCU must send a read command frame first before read operation.

Figure 14

When CYP1840 is in communication mode, the frame identification byte {0x58} indicates that the data communication operation is data reading. After receiving the register address, CYP1840 starts to shift out the data in the register on the rising edge of SCLK (Figure 14). All remaining bits of the register data are shifted out on subsequent rising SCLK edges. Therefore,on the falling edge of SCLK, an external device can sample the output data of the SPI. Once the read operation is completed, SPI re-enters the communication mode. SDO enters a high-impedance state on the falling edge of the last SCLK signal.

Fault-tolerant mechanism of SPI interface

SPI supports soft reset function, reset SPI interface individually by sending 6bytes of 0xFF.

UART Communication methods

Summarize

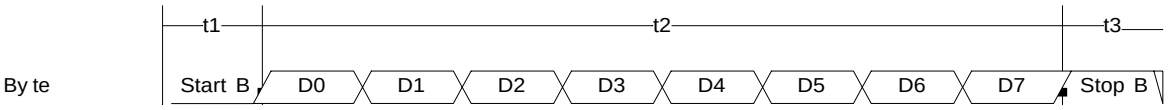
CYP1840 supports UART communication. The UART interface only requires two low speed optocouplers to achieve isolated communication.

Baud rate: 4800bps Check bits: None Data bits: 8 Stop bits: 1.5 Slave mode, half-duplex communication

Description

UART port Settings: Communication baud rate is 4800bps, no parity, stop bit 1.5 .

Byte Formation



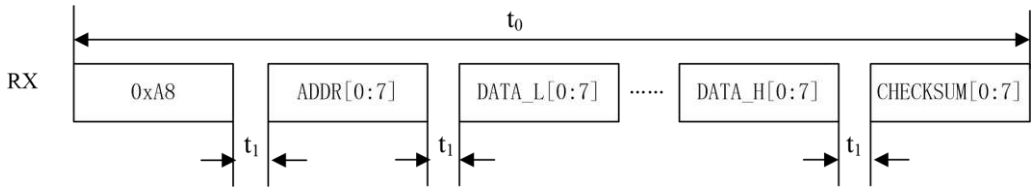
Start bit low duration: t1=208us;

Valid data bit duration: t2=208*8=1664usStop

bit high duration: t3=208us+104us

Write Timing

The data write sequence of the host UART is shown in the figure below. The host sends command bytes (0xA8) first, then write address bytes (ADDR), then sends data bytes in sequence, and finally checksum bytes.

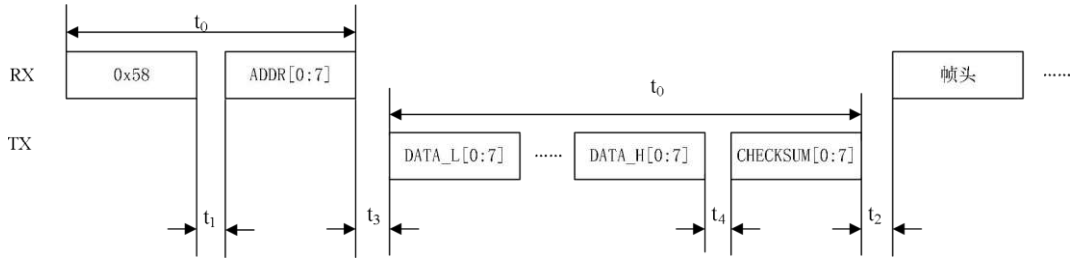


(0xA8) is the frame identification byte for the write operation. ADDR is the internal target register in CYP1840 corresponding to the write operation.

The checksum byte is（（0xA8+ADDR+Data_L+Data_M+Data_H）& 0xFF）and then bitwise inverted.

Read Timing

The timing of reading data is shown below. MCU first sends the command byte (0x58) and the address of the target register (ADDR), and then CYP1840 sends data bytes in sequence. Finally sends the checksum byte.



(0x58) is the frame identification byte for the read operation. ADDR is the internal target register in CYP1840 corresponding to the read operation.

The checksum byte is（（0x58+ADDR+Data_L+Data_M+Data_H）& 0xFF）and then bitwise inverted.

Timing Description ：

	Description	Min	Type	Max	Unit
t1	Interval between MCU sending bytes	0		20	mS
t2	Frame interval	0.5			uS
t3	Interval between the end of MCU sending register address and CYP1840 sending byte during read operation		72		uS
t4	Interval between CYP1840 sending bytes		116		uS

Packet sending mode

After received the command "(0x58) + 0xAA", CYP1840 will return a full electrical parameter data packet. The returned data packet has a total of 35 bytes, and 4800bps takes 77ms.The specific format is：Frame head（1byte head）→Current A fast effective value（3byte IA_FAST_RMS）→Current A effective value（3byte IA_RMS）→reserved（3byte）→Effective voltage（3byte V_RMS）→reserved（3byte）→Channel A power value（3byte A_WATT）→reserved（3byte）→Channel A pulse meter value（3byte CFA_CNT）→reserved（3byte）→Internal thermometer value（2byte TPS1 + 1byte 0）→External thermometer value（2byte TPS2 + 1byte 0）→Checksum value（1byte CHECKSUM）.

Full electrical parameter data packet format:

Name	No.	Value	Name	No.	Value
Frame head	0	Head（0x55）	reserved	19	reserved
IA_FAST_RMS	1	IA_FAST_RMS_l		20	reserved
	2	IA_FAST_RMS_m		21	reserved
	3	IA_FAST_RMS_h	CFA_CNT	22	CFA_CNT_l
IA_RMS	4	IA_RMS_l		23	CFA_CNT_m
	5	IA_RMS_m		24	CFA_CNT_h
	6	IA_RMS_h	reserved	25	reserved
reserved	7	reserved		26	reserved
	8	reserved		27	reserved
	9	reserved	TPS1	28	TPS1_l
V_RMS	10	V_RMS_l		29	TPS1_m
	11	V_RMS_m		30	0x00
	12	V_RMS_h	TPS2	31	TPS2_l
reserved	13	reserved		32	TPS2_m
	14	reserved		33	0x00
	15	reserved	checksum	34	checksum
A_WATT	16	A_WATT_l			
	17	A_WATT_m			
	18	A_WATT_h			

checksum=（（0x58 + 0x55 + data1_l + data1_m + data1_h +…….）& 0xff）and then bitwise inverted.

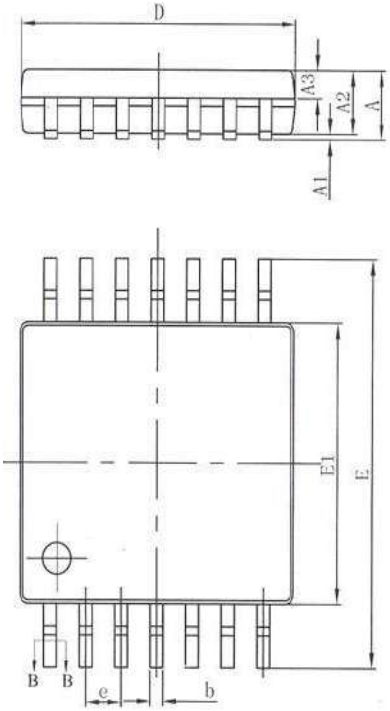
Protection mechanism of UART interface

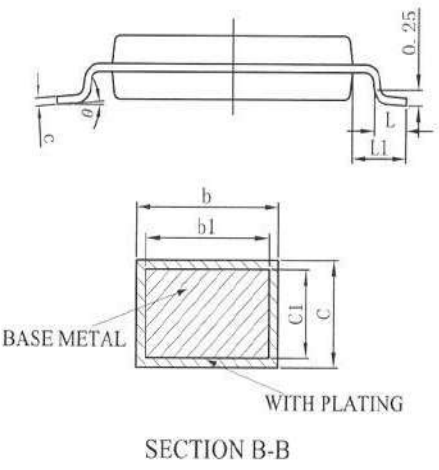
UART communication has a timeout protection mechanism. If the interval between bytes exceeds18.5ms, the UART interface will automatically reset.

If the frame identification byte is incorrect or the checksum byte is incorrect, the frame data will bediscarded.

UART module reset: The RX pin is pulled high after the low-level exceeds 6.65mS, and the UARTmodule will be reset.

Package Information（TSSOP14）





SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	—	—	1.20
A1	0.05	—	0.15
A2	0.90	1.00	1.05
A3	0.39	0.44	0.49
b	0.20	—	0.28
b1	0.19	0.22	0.25
c	0.13	—	0.17
c1	0.12	0.13	0.14
D	4.90	5.00	5.10
E1	4.30	4.40	4.50
E	6.20	6.40	6.60
e	0.65BSC		
L	0.45	0.60	0.75
L1	1.00BSC		
θ	0	—	8°

Special Instructions

The company reserves the right of final interpretation of this specification.

Version Change Description

Version：V1.03 Author：Lifeng Liu Time：2021.9.09

Modify the record：

1. Re-typesetting the manual and checking some data

Statement

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